Riemann Surfaces Assignment 1

1. (Orientation) Let B(V) denote the set of all *ordered basis* of a finite dimensional real vector space V. Two ordered basis are called *equivalent* if the map that sends one to the other has positive determinant.

a) Show that this is an equivalence relation on B(V) and that there are only two equivalence classes. Each equivalence class is called an *orientation* for V. Let $f: V_1 \to V_2$ be an invertible linear map between oriented vector spaces. Define what it means to say f is *orientation preserving*.

b) Let W be a finite dimensional complex vector spaces and $V = W_{\mathbb{R}}$ its underlying real vector space. Show that V has a canonical orientation. If $f: W_1 \to W_2$ is a \mathbb{C} - linear invertible map, show that the induced map between real vector spaces is orientation preserving. How all this is related to the fact that a Riemann surface has a canonical orientation and an (invertible) holomorphic map is orientation preserving?

- 2. Let X be a compact connected Riemann surface and $F: X \to \mathbb{C}$ be a holomorphic function. Show that F is constant. (Hint: use maximum principle from complex analysis.)
- 3. A meromorphic function on a Riemann surface X is, by definition, a holomorphic map $F: X \to \mathbb{C}P^1$ which is not identically equal to ∞ .

a) Define *zeros* and *poles* and their *orders* for a meromorphic function. (You have to show that your definitions are independent of the choice of holomorphic coordinates). Why the *residue* of a meromorphic function at a pole is not well-defined?

b) Let $\frac{f(z)}{g(z)}$ be a rational function. Show that it defines a meromorphic function on $\mathbb{C}P^1$. Find its zeros and poles and their orders in terms of linear factorizations of f and g. What is the *degree* of this map ? Let n_i

denote the order of zeros and p_j the orders of poles of a meromorphic function on $\mathbb{C}P^1$. Show that

$$\sum n_i = \sum p_j.$$

c) Let K(X) denote the set of meromorphic functions on X. Show that K(X) is naturally a *field*.

d) Show that any meromorphic function on $\mathbb{C}P^1$ is a rational function and hence $K(\mathbb{C}P^1) = \mathbb{C}(z)$ is the field of rational functions in one variable.

e) Show that the poles and zeros of a meromorphic function on $\mathbb{C}P^1$ can be placed anywhere you wish, provided they are the same in muber.

f) Let $p_1, p_2, \ldots p_n$ be a collection of points on $\mathbb{C}P^1$, repetitions permitted, and let L be the space of meromorphic functions with poles of orders at most d_i at p_i . Show that L is a complex vector space of dimension $\sum d_i + 1$.

4. Let $\alpha_1 < \alpha_2 < \cdots < \alpha_{2g+2}$ be real numbers. a) Sketch a graph of real points of the curve

$$y^2 = \prod_{i=1}^{2g+2} (x - \alpha_i)$$

b) By using homogenization, show that by adding two points, one obtains a compact Riemann surface.

- 5. Prove Euler's formula for homogeneous functions we used in class.
- 6. Show that the set of points (x, y) is \mathbb{C}^2 where $y^2 = sin(x)$ is naturally a Riemann surface.

7. a) Use Liouville's theorem to show that $Aut(\mathbb{C})$ consists of maps $z \to az + b$ for $a \neq 0$.

b) Show that the automorphisms of the Riemann sphere are given by Möbius maps $PSL(2, \mathbb{C})$.

c) Use the Schwartz Lemma to identify the stabilizer of 0 is Aut(D) and hence identify Aut(D) and Aut(H).

8. Let $X(R_1, R_2)$ denote the open annular region between concentric circles of radius R_1 and R_2 in the plane. Show that $X(R_1, R_2)$ is (biholomorphically) equivalent to $X(R'_1, R'_2)$ iff

$$\frac{R_1}{R_2} = \frac{R_1'}{R_2'}.$$

Conclude that there are uncountabaly many inequivalent Riemann surfaces with the topology of an annular region (= cyclinder).