# THE UNIVERSITY OF WESTERN ONTARIO London Ontario

# **Applied Mathematics Ph.D. Comprehensive Examination**

#### Part I: 9:00 am - 12:00 pm, 1 May 2024

#### **Instructions:**

- The comprehensive exam consists of two parts. This is Part I. Part I consists of mandatory problems and covers basic material. In Part I, 80% is required for a passing grade.
- You may use a calculator, pen, and pencil. NO other aids are allowed. Your calculator must NOT be capable of wireless communication or capable of storing and displaying large text files.

## Do ALL of the questions in the following four sections

### 1. Calculus

- (a) (i) Show that  $g(x) = \frac{x}{x-1}$  is one-to-one. (ii) Assume a function f(x) satisfies  $f\left(\frac{x}{x-1}\right) = \frac{3x-1}{3x+1}$ , find the explicit formula for f(x).
- (b) Let  $f(x) = (\ln x)^2$  and  $g(x) = \frac{1}{x^{\alpha}}$  for x > 0, where  $\alpha$  is any positive real number. Which of these two functions tends to  $\infty$  faster when  $x \to 0^+$ ? Show your work to support your conclusion.
- (c) Let  $b(x) = px^2e^{-x}$  where p is a positive parameter. Find the range for p within which b(x) < x for all  $x \in (0, \infty)$  (hence, b(x) has no positive fixed point).
- (d) The improper integral  $I = \int_0^\infty e^{-x^2} dx$  is widely seen and used. Do the following for I.
  - (i) Explain why it is convergent.
  - (ii) Find the value of I by relating  $I^2$  to the limit of a double integral in  $\mathbb{R}^2$ . [Hint: use symmetry of integrals and polar coordinates.]

#### 2. Linear Algebra

- (a) Consider the linear system AX = B where  $A = (a_{i,j})_{m \times n}$  is an  $m \times n$  real matrix,  $B = (b_1, b_2, \dots, b_m)^T \in \mathbb{R}^m$  is a real vector and  $X = (x_1, x_2, \dots, x_n)^T$  is the unknown vector. Note that A can also be expressed in terms of column vectors:  $A = [A_1, A_2, \dots, A_n]$  where  $A_j = (a_{1j}, a_{2j}, \dots, a_{nk})^T$  for  $j = 1, 2, \dots n$ .
  - (i) There are several equivalent necessary and sufficient conditions <u>on A and B</u> for AX = B to be compatible (i.e., having solution), state one of them.
  - (ii) State a necessary and sufficient condition <u>on A</u> under which, AX = B is compatible for every  $B \in \mathbb{R}^m$ .
  - (iii) When m = n, state <u>an alternative condition</u> for each of the above two questions.
  - (iv) Explain why AX = B cannot have precisely two (or three or four) solutions.
- (b) Let  $v_1 = (1, -1, 1)$  and  $v_2 = (1, 1, -1)$  and W be the subspace in  $\mathbb{R}^3$  spanned by  $v_1$  and  $v_2$ .
  - (a) Find the orthogonal projection of v = (1, 1, 1) in W.
  - (b) Find the distance of v to W.

- (c) Consider the polynomials x 1,  $x^2 2$  and  $x^3 3$ .
  - (i) Determine whether these three polynomials are linearly dependent or linearly independent. Show your work.
  - (ii) Do these three vectors span  $P^{(3)}$  (the vector space of all polynomials with degree no more than 3)? Justify your answer.
- (d) Find a basis and the dimension of the kernel space KerA of the matrix

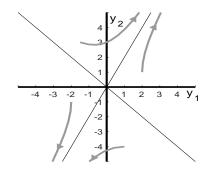
$$A = \left(\begin{array}{rrrr} 1 & 2 & -1 & 3 \\ 3 & 0 & 3 & -3 \end{array}\right).$$

#### 3. Numerical Methods

- (a) Consider the system of equations  $f(u, v) = v^4 u^4 = 0$ ,  $g(u, v) = u^2 + v^2 1 = 0$ . Find the Jacobian Matrix of this system and set up the main iteration step of Newton's method. Starting from the initial point (u, v) = (-1, +1) use 2 Newton iterations to find an approximate solution of the system. Check the accuracy of your solution.
- (b) The one-dimensional version of Newton's Method for solving F(x) = 0 for differentiable F(x) locally converges quadratically to roots where  $F'(x) \neq 0$ . Briefly without calculations state the analygous result for differentiable systems such as the one in (a).

# 4. Ordinary differential equations

- (a) Find the general solution to:  $y' 2y = e^{-2x}y^2$ .
- (b) Give a particular solution to  $y'' y' = 10 \cos 2x$ .
- (c) Four solution trajectories to  $\vec{y}' = A\vec{y}$ , where A is a real  $2 \times 2$  matrix, are illustrated in grey on the  $(y_1, y_2)$  plane. Give possible eigenvalues and eigenvectors of A (many correct answers are possible). Using these, write the general solution.



(d) i. Give the general solution to

$$2xy - y\sin(xy) + (x^2 - x\sin(xy))\frac{dy}{dx} = 0, \ x > 0$$

- ii. Find the solution if y(1) = 0.
- iii. If you plotted the solution from Part ii on the (x, y) plane, what slope would it have at this initial condition?
- iv. Does a solution exist for initial condition  $x_0 = 1$ ,  $y_0 = \pi/2$ ? Explain why or why not.